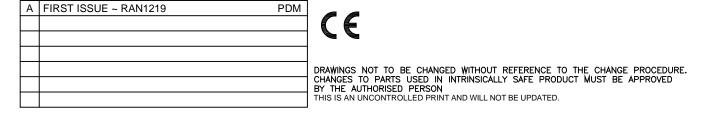
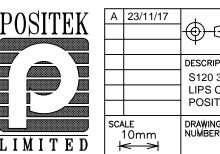
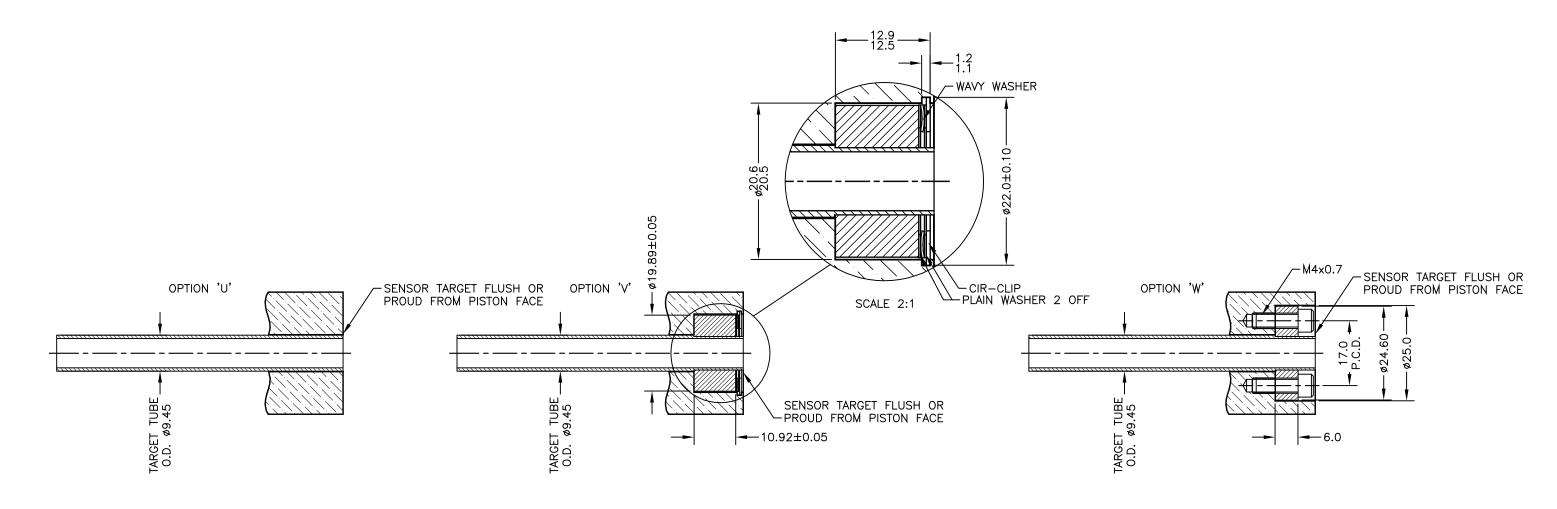


MAXIMUM WORKING PRESSURE; HYDRAULIC / PNEUMATIC CYLINDER AND EXTERNAL WATER PRESSURE MUST NOT EXCEED 350 BAR. WHERE THE FREE END OF THE CABLE IS TO BE TERMINATED IN A SUBMERGED POSITION, ADEQUATE SEALING MUST BE PROVIDED TO PROTECT CONNECTIONS.

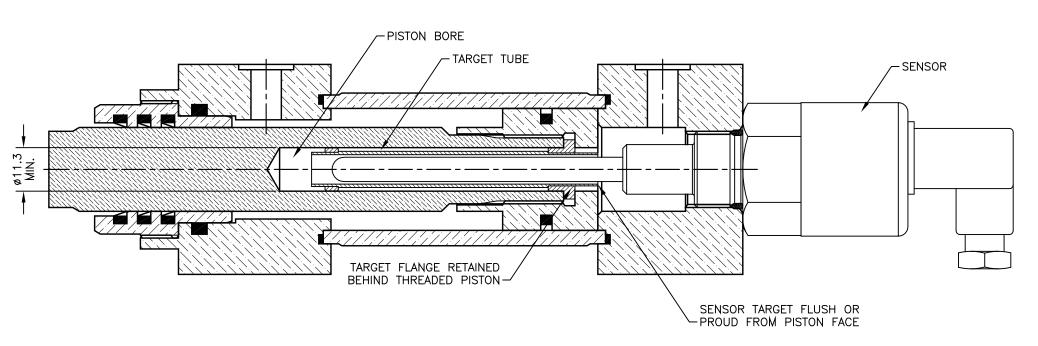




A 23/11/17	<b>♦</b> □	CHECKED BY RDS	X ±0.4 X.X ±0.2 X.XX ±0.1 DIMS mm
	DESCRIPTION S120 350 BAR SUBMERSIBLE LIPS CYLINDER LINEAR POSITION SENSOR		
SCALE 10mm	DRAWING NUMBER	\$120-11 SHEE	_ '_'





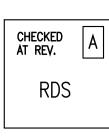


Α	FIRST ISSUE.	RDS
В	REDRAWN.	PDM
С	WORDING AMMENDED	RDS
D	TARGET NOTES AMENDED - RAN1349	PDM

DRAWINGS NOT TO BE CHANGED WITHOUT REFERENCE TO THE CHANGE PROCEDURE.
CHANGES TO PARTS USED IN INTRINSICALLY SAFE PRODUCT MUST BE APPROVED
BY THE AUTHORISED PERSON
THIS IS AN UNCONTROLLED PRINT AND WILL NOT BE UPDATED.

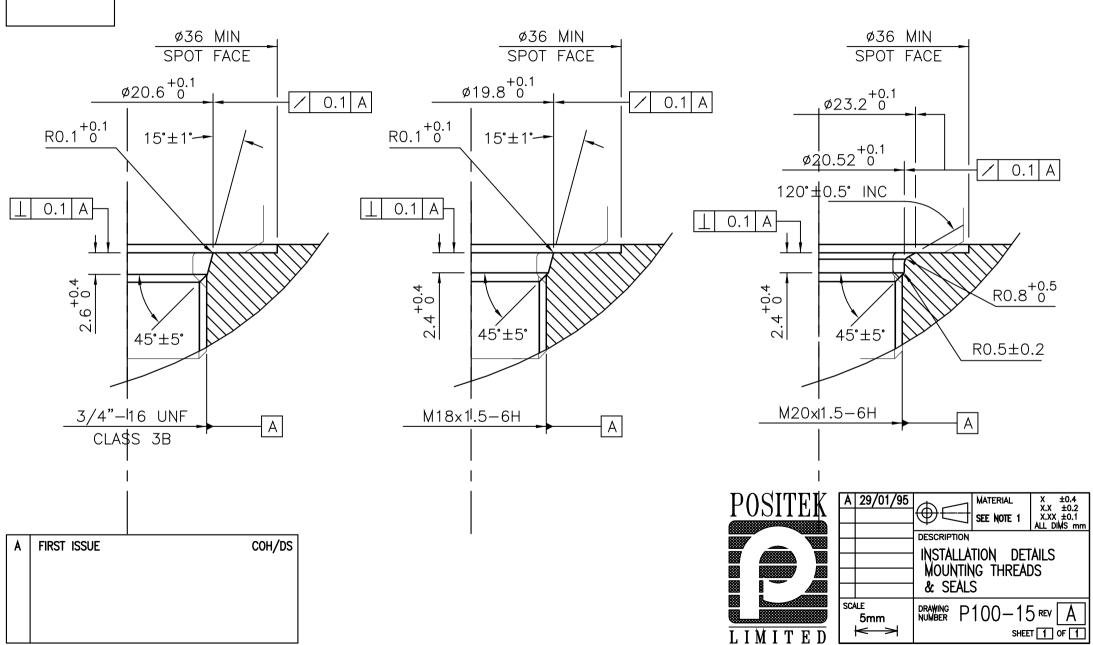


Α	28/06/95		CHECKED BY	
В	04/10/11	<del>((()) [[-]</del>	RDM	X.X ±0.2 X.XX ±0.1
O	26/10/17	7		DIMS mm
D	22/01/21	DESCRIPTION	l	
		1	TARGET TU	BE
		FITTING C	PTIONS	
SCA	LE 10mm	DRAWING F	100-12	REV D
١.	OHILL	''כיייבוי		
†	<del></del>		SHEE	T 1 OF 1



DRAWING NOT TO BE CHANGED WITHOUT REFERENCE TO THE CHANGE PROCEEDURE. CHANGES TO PARTS USED IN INTRINSICALLY SAFE PRODUCT MUST BE APPROVED BY THE AUTHORISED PERSON

THIS IS AN UNCONTROLLED PRINT AND WILL NOT BE UPDATED



TARGET TUBE OPTION NOTES:-1. SPECIFY TUBE MATERIAL; CODE:—

'R' STAINLESS STEEL 316 \( \text{99.45}. \)

'S' ALUMINIUM 6063 \( \text{83/8"} \) (9.2-9.8). NOTE! ONLY AVAILABLE WITH P100 OR P106 VERSIONS.

2. SPECIFY FLANGE TYPE; CODE: 'U', 'Vx', Wx' OR 'Xx' \( \text{SEE} \) DETAILS BELOW.

3. SPECIFY DIMENSION 'x' (mm), NOT APPLICABLE CODE 'U' PLAIN TUBE. -LENGTH: DISPLACEMENT + 30 (FOR 100mm DISPLACEMENT LENGTH = 130)-STANDARD PLAIN, CODE 'U' O.D. SEE NOTE 1. I.D. SEE NOTE 1. DIM 'x' -SEE NOTE 3. -MIN. 10.92 ø19.94 19.84 PENNY & GILES HLP100, CODE 'V' STAINLESS STEEL DIM 'x' SEE NOTE 3. ø4.4 2 PLACES-MIN. 6 Ø24.60 -P.C.D. ø17.0 TEMPOSONICS (M4 FIXING), CODE 'W' STAINLESS STEEL 6.0 ø11.20 ¶1.15 ø11.20 DIM 'x' SEE NOTE 3.→ MIN. 7 7.0 ø15.50 PARKER HANNIFIN, CODE 'X' STAINLESS STEEL STAINLESS STEEL CHECKED BY X ±0.4 X.X ±0.2 RDM X.XX ±0.1 DIMS mm E 16/10/06 F 24/09/08 TARGET TUBE MOUNTING NOTES, SEE DRAWING P100-12. G 13/11/08 E MATERIAL OPTION REMOVED. H 11/12/12 PDM F MAT'L OPTION REINSTATED RAN221. PDM J 23/07/14 TARGET TUBE AND FLANGE OPTIONS (LIPS 100/106) K 30/11/16 G X DIM FOR PH FLANGE SHOWN RAN225 RDS H 9.45 WAS 9.5 RAN396 L 08/11/22 J REDRAWN, PH FLANGE ROTATED RAN507. PDM DRAWINGS NOT TO BE CHANGED WITHOUT REFERENCE TO THE CHANGE PROCEDURE. CHANGES TO PARTS USED IN INTRINSICALLY SAFE PRODUCT MUST BE APPROVED BY THE AUTHORISED PERSON SCALE 5mm DRAWING TG24-11 REV L K NOTE 1 AMENDED ~ RAN1114. PDM LIMITED SHEET 1 OF 1 L 'x' WAS 'n' ~ RAN1309 PDM THIS IS AN UNCONTROLLED PRINT AND WILL NOT BE UPDATED.



## S120 350 BAR SUBMERSIBLE CYLINDER – LINEAR POSITION SENSOR High-resolution position feedback for hydraulic and pneumatic cylinders

- Non-contacting inductive technology to eliminate wear
- Travel set to customer's requirement
- Compact and self-contained
- High durability and reliability
- High accuracy and stability
- Sealing to IP68 350 Bar

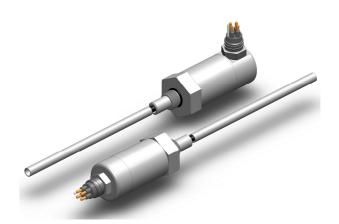
As a leading designer and manufacturer of linear, rotary, tilt and intrinsically safe position sensors, Positek® has the expertise to supply a sensor to suit a wide variety of applications.

Our S120 is an affordable, durable, highaccuracy position sensor designed for arduous underwater hydraulic or pneumatic cylinder position feedback applications where service life, environmental resistance and cost are important. It is particularly suitable for OEMs seeking good sensor performance for arduous applications such as industrial machinery.

Overall performance, repeatability and stability are outstanding over a wide temperature range. The unit is highly compact and space-efficient, being responsive along almost its entire length. Like all Positek® sensors it provides a linear output proportional to travel. Each unit is supplied with the output calibrated to the travel required by the customer, any stroke from 0-5mm to 0-800mm and with full EMC protection built in.

The sensor is very rugged, being made of stainless steel with an inert fluoropolymersheathed probe with a stainless steel target tube. The sensor is easy to install in cylinders and has a wide range of mechanical and electrical options.

Environmental sealing is to IP68 350 Bar. The maximum system pressure is limited to 350 Bar (Water pressure plus hydraulic pressure).



### **SPECIFICATION**

Di	m	e	ns	io	n	s	

Body diameter Body Length (to seal face) 80.3 mm (axial), 88.8 mm (radial) Probe Length (from seal face) calibrated travel + 58 mm

Probe Length (11011 sed lace) Calibrated travel + 30 mm

For full mechanical details see drawing \$120-11

ndependent Linearity ≤ ± 0.25% FSO @ 20°C - up to 450 mm
≤ ± 0.5% FSO @ 20°C - over 450 mm
≤ ± 0.1% FSO @ 20°C\* available upon request. Independent Linearity

Sensors with calibrated travel from 10 mm up to 400 mm.

**Temperature Coefficients** < ± 0.01%/°C Gain & < ± 0.01%FS/°C Offset **Frequency Response** 

> 10 kHz (-3dB) > 300 Hz (-3dB) 2 wire 4 to 20 mA Resolution

Infinite < 0.02% FSO **Environmental Temperature Limits** -4°C to +50°C -4°C to +50°C Operating Storage

Sealing IP68 350 Bar **Hydraulic Pressure** 350Bar Absolute **EMC Performance** EN 61000-6-2, EN 61000-6-3

Vibration IEC 68-2-6: 10 g Shock IEC 68-2-29:

Limit of 350 Bar for water pressure + hydraulic pressure 40 g

**MTBF** 350,000 hrs 40°C

**Drawing List** 

S120-11 Sensor Outline

Typical Target Installation details Mounting Thread details P100-12 P100-15 TG24-11 Optional Target Tube Flange details Drawings, in AutoCAD® dwg or dxf format, available on request.

Do you need a position sensor made to order to suit a particular installation requirement or specification? We'll be happy to modify any of our designs to suit your needs please contact us with your requirements.



# **S120** 350 BAR SUBMERSIBLE CYLINDER – LINEAR POSITION SENSOR High-resolution position feedback for hydraulic and pneumatic cylinders

## How Positek's technology eliminates wear for longer life

Positek's Inductive technology is a major advance in displacement sensor design. Our displacement transducers have the simplicity of a potentiometer with the life of an LVDT/RVDT.

Our technology combines the best in fundamental inductive principles with advanced micro-electronic integrated circuit technology. A Positek sensor, based on simple inductive coils using Positek's ASIC control technology, directly measures absolute position giving a DC analogue output signal. Because there is no contact between moving electrical components, reliability is high and wear is eliminated for an exceptionally long life.

Our technology overcomes the drawbacks of LVDT technology – bulky coils, poor length-to-stroke ratio and the need for special magnetic materials. It requires no separate signal conditioning.

We also offer a range of ATEX-qualified intrinsicallysafe sensors.

### **TABLE OF OPTIONS**

**CALIBRATED TRAVEL:** Factory set to any length from 0-5mm to 0-800mm (e.g. 254mm)

#### **ELECTRICAL INTERFACE OPTIONS**

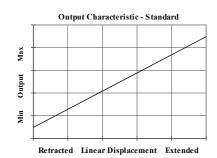
OUTPUT SIGNAL Standard:	SUPPLY INPUT	OUTPUT LOAD
0.5-4.5V dc ratiometric Buffered:	$+5V$ dc nom. $\pm$ 0.5V.	5kΩ min.
0.5-4.5V dc ±5V dc 0.5-9.5V dc ±10V dc	+24V dc nom. + 9-28V. ±15V dc nom. ± 9-28V. +24V dc nom. + 13-28V. ±15 V dc nom. ± 13.5-28V.	$5k\Omega$ min. $5k\Omega$ min. $5k\Omega$ min. $5k\Omega$ min.
Supply Current	10mA typical, 20mA maximum.	
4-20mA (2 wire) (3 wire sink) (3 wire source)	+24 V dc nom. + 18-28V. +24 V dc nom. + 13-28V. +24 V dc nom. + 13-28V.	$300\Omega$ @ 24V. $950\Omega$ @ 24V. $300\Omega$ max.
CONNECTOR	Wet mate 4 pin MC BH-4-M (ax Supplied with a connector and cable assembly as standard. Mating connector with longer le	0.5 m, 4x0.5mm <sup>2</sup>

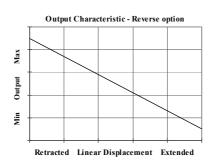
#### **MOUNTING THREAD OPTIONS**

M18 or  $\frac{3}{4}$  UNF 40 mm hex A/F, Ø 40 mm seal face. Supplied with O-ring seal.

#### **FLANGE OPTIONS**

Penny & Giles HLS120, Temposonics (M4 fixing) and Parker Hannifin cylinders versions available.

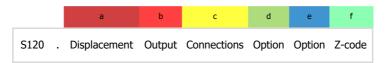




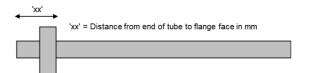
For further information please contact:

www.positek.com
sales@positek.com

## S120 350 Bar Submersible Cylinder – Linear Position Sensor



a <b>Displacement</b> (mm)		Value			
Displacement in mm	e.g. 0 - 254 mm	254			
b <b>Output</b>					
	Supply V do				
V <sub>s</sub> (tolerance)	Output	Code			
+5V (4.5 - 5.5V)	0.5 - 4.5V (ratiometric with supply)	A			
±15V nom. (±9 - 28V)	±5V	В			
+24V nom. (13 - 28V)	0.5 - 9.5V	C			
±15V nom. (±13.5 - 28V)	±10V	D			
+24V nom. (18 - 28V)	4 - 20mA 2 wire	E			
+24V nom. (13 - 28V)	4 - 20mA 3 wire Sink	F			
+24V nom. (9 - 28V)	0.5 - 4.5V	G			
+24V nom. (13 - 28V)	4 - 20mA 3 wire Source	Н			
c Connections		Code			
Connector - Radial	IP68 350 Bar Wet mate 4 pin MC	K50			
Connector - Axial	BH-4-M plus pre-wired mating connector with 50 cm 4-core cable.	J50			
d Mounting Thread		Code			
3/4 16 UNF	Hex. 40 mm A/F, Ø 40 mm seal	Р			
M18 x 1.5	face. Supplied with O-ring seal.	т			
See P100-15 Drawing for Mating Thread Details.					
e Target Tube Mounti	ing Flange	Code			
None		U			
Penny & Giles HLP100	Please specify flange position in mm.	Vxx			
Temposonics (M4 fixing)	eg. W17.5 specifies a Tempo style	Wxx			
Parker Hannifin	flange fitted 17.5 mm from the front face	Xxx			
See TG24-11 Drawing for Target Details.					
f Z-code Code					
$\leq \pm 0.1\%$ @20°C Independent Linearity displacement between 10mm & 400mm only!					





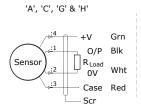
## **Installation Information**

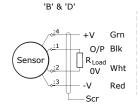
## S120 350 BAR SUBMERSIBLE CYLINDER – LINEAR POSITION SENSOR

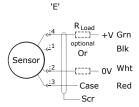
Output Option	Output Description:	<b>Supply Voltage:</b> V <sub>s</sub> (tolerance)	<b>Load resistance:</b> (include leads for 4 to 20mA O/Ps)
A	0.5 - 4.5V (ratiometric with supply)	+5V (4.5 - 5.5V)	≥ 5kΩ
В	±5V	±15V nom. (±9 - 28V)	≥ 5kΩ
С	0.5 - 9.5V	+24V nom. (13 - 28V)	≥ 5kΩ
D	±10V	±15V nom. (±13.5 - 28V)	≥ 5kΩ
E	4 - 20mA 2 wire Current Loop	+24V nom. (18 - 28V)	$\approx 0$ - $300\Omega$ max. @24V $\sim 1.2$ to 6V across 3000 $~\{R_L$ max. = (V_s - 18) / $20^{-3}\}$
F	4 - 20mA 3 wire Sink	+24V nom. (13 - 28V)	$\approx 0$ - 950 $\Omega$ max. @24V $\sim$ 3.8 to 19V across 950 $\Omega$ {RL max. = (Vs - 5) / 20 $^{-3}$ }
G	0.5 - 4.5V	+24V nom. (9 - 28V)	≥ 5kΩ
н	4 - 20mA 3 wire Source	+24V nom. (13 - 28V)	$\approx 0$ - $300\Omega$ max. $\sim 1.2$ to 6V across $300\Omega$

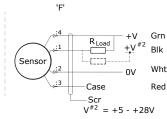
Connector Pin Layout: MC BH 4 M (face view)





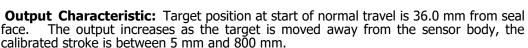


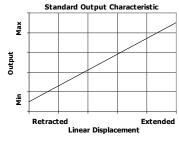




**Mechanical Mounting:** Via mounting thread, maximum tightening torque: 100Nm. See drawing P100-15, Installation Details Mounting Threads & Seals. An O ring seal is provided, size BS908 for 3/4 UNF thread or 14.3 x 2.4 for M18 thread. Install the target tube using the flange provided or fix directly into the piston rod using adhesive for instance, the end of the target tube can be proud or flush with the piston end face as

N.b. cable free end must be appropriately terminated to prevent water ingress into the cable. **See page 2 for connector handling instructions.** The sensor is sealed to IP68 350 Bar.





## **Incorrect Connection Protection levels:**

Not protected – the sensor is **not** protected against either reverse polarity or over-voltage. The risk of damage should be minimal where the supply current is limited to less than 50mA.

B & D Supply leads diode protected. Output must not be taken outside ± 12V.
Supply leads diode protected. Output must not be taken outside 0 to 12V.

E, F & H Protected against any misconnection within the rated voltage.



## **Installation Information**

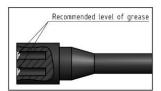
## S120 350 BAR SUBMERSIBLE CYLINDER – LINEAR POSITION SENSOR

## Handling

- Always apply grease before mating
- Disconnect by pulling straight, not at an angle
- Do not pull on the cable and avoid sharp bends at cable entry
- When using a bulkhead connector, ensure that there are no angular loads
- Do not over-tighten the bulkhead nuts
- SubConn<sup>®</sup> connectors should not be exposed to extended periods of heat or direct sunlight. If a connector becomes very dry, it should be soaked in fresh water before use

### Greasing and mating above water (dry mate)

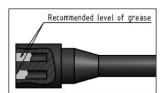




- Connectors must be greased with Molykote 44 Medium before every mating
- A layer of grease corresponding to minimum 1/10 of socket depth should be applied to the female connector
- The inner edge of all sockets should be completely covered, and a thin transparent layer of grease left visible on the face of the connector
- After greasing, fully mate the male and female connector in order to secure optimal distribution of grease on pins and in sockets
- To confirm that grease has been sufficiently applied, de-mate and check for grease on every male pin. Then re-mate the connector.

## Greasing and mating under water (wet mate)





- Connectors must be greased with Molykote 44 Medium before every mating
- A layer of grease corresponding to approximately 1/3 of socket depth should be applied to the female connector
- All sockets should be completely sealed, and transparent layer of grease left visible on the face of the connector
- After greasing, fully mate the male and female connector and remove any excess grease from the connector joint

#### Cleaning

- General cleaning and removal of any accumulated sand or mud on a connector should be performed using spray based contact cleaner (isopropyl alcohol)
- New grease must be applied again prior to mating